

# User Manual Scrubber 50[V4.2\_Disc Brush] AIO

Gausium Technical Service and Operations Center

# **Change Records:**

Document Version	Last Update	Change Type	Software Version Basis	Machine Version Basis	Revised Content	Revised by
CN_V1.0	24.07.26	Α	A2-00-1	V4.2 Disc Brush	V4.1/V4.2 Disc Brush(AIO)	Nine

Change Types: A = Add; M = Modify; D = Delete.

**Software Version Basis**: The software version used during the development of the document. Differences in software versions may affect certain operations on the device.

**Machine Version Basis**: The machine version used during the development of the document. Differences in machine versions may affect certain operations on the device.

**Disclaimer**: This document is for reference only. If there are discrepancies between the document and the actual situation, please consult your Gausium contact engineer for the correct operational procedures.

<sup>\*</sup> Gausium continuously upgrades and optimizes its software to ensure users enjoy a more seamless and enhanced experience.



Emergency Stop

Startup

Manual Mode

Shutdown

Auto Mode

Manual Move

Scheduling

Charging

Positioning Transfer

Wastewater

Clean Water Disposal

View

Alarms

Drainage



Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency Stop

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

# Appearance – Front Side

Top Lid

Front Tilt Camera (Sensor)

Front Door

LiDAR (Sensor)

Small Aperture Laser (Sensor)

Left and Right Cameras
(Sensors)

Anti-Collision Bumper



# Appearance - Rear Side



Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency Stop Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

Alarms

# Appearance - Left Side



# Appearance - Right Side



Right Door

Anti-Collision Bumper -Left

Manual Drain Hose

Left Door

Anti-Collision Bumper -Right



Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal

Wastewater Drainage

**Scrubber 50 User** Manual

Manual

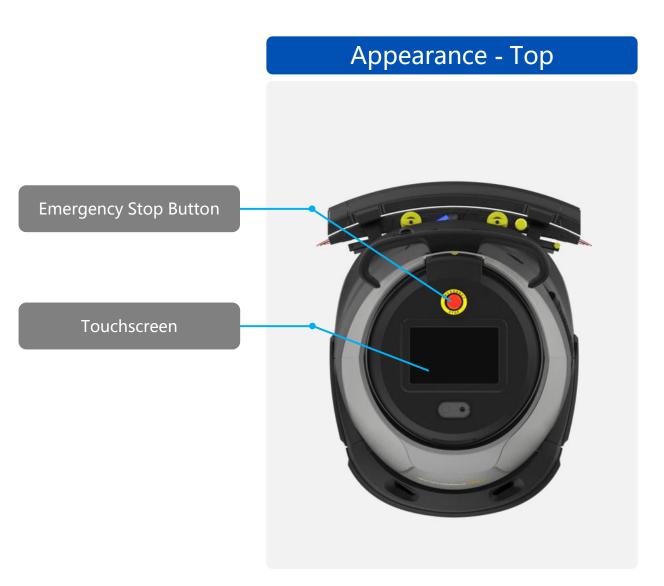
Mode

Auto Mode

Scheduling

Positioning Transfer

View Alarms



Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Start

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

# Startup



#### **Precautions:**

1. If the air switch is in the "On" position and the key switch is set to "ON" but the machine still won't start, try using the charger to charge the battery, which may activate the battery.



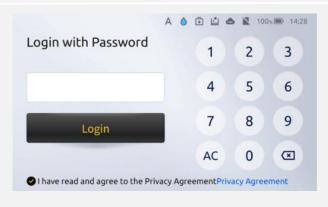
Press the power button.



Turn the key switch to the "ON" position and hold it there until the machine's screen lights up.

2





- 1. Enter the login password, which is set to **123456** by default.
- 2. Click **Login**.

Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

# Shutdown



#### **Precautions:**

- 1. Do not turn off the power button directly while the machine is on. Before turning off the power button, you must first use the key switch to shut down the machine :
- 2. Precautions for Long-Term Shutdown and Storage:
- ① After shutting down normally, please remove all consumables, including the squeegee blades and brush pads;
- ② Perform a comprehensive maintenance check on the machine;
- ③ Charge the machine once a



Turn the key switch to the "ON" position and hold it there until the machine's screen turns off;





Turn off the power button;



Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Manual Mode

Auto Mode

Scheduling

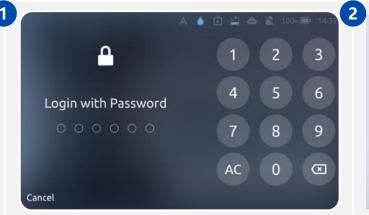
Positioning Transfer View Alarms

## Manual Move



#### **Precautions:**

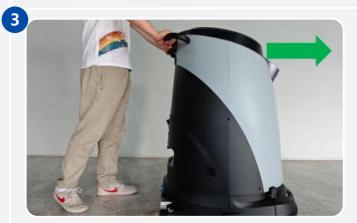
1. Do not forcefully push the machine if it is in automatic mode.



Log in to the machine with a password;



Tap "Manual Mode" to switch the machine mode to manual;



Use the handle to push the machine. If the machine cannot be pushed, check the emergency stop button to ensure it has not been activated.

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

Manual Charging

Method 1: Wired

Charging



# Method 2: Manual Docking



# **Auto Charging**



Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

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Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

# Wired Charging



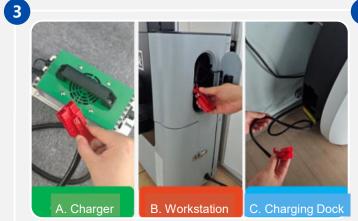
**Precautions:**None



ABC. Manually move the machine next to the charger/ workstation/ charging dock. For instructions on how to Manually move the machine, refer to: Manual Move.



Pull out the dustproof rubber cover from the charging port on the left side of the machine.



A. Hold the red charging plug of the charger.

- B. Take the red charging plug from the left side door of the workstation.
- C. Take the red charging plug from the right side door of the charger.



Insert the red charging plug into the machine's charging port.

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

# Wired Charging



**Precautions:**None

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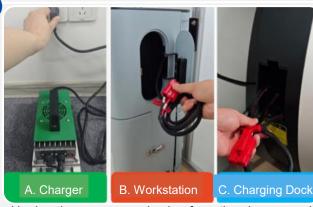
ABC. Connect the power supply to the charger/workstation/charging dock.



Check the machine's screen to confirm that the robot is in charging mode.



- 1. Once the battery is fully charged to 100%, remove the red charging plug.
- 2. Reattach the dustproof rubber cover to the charging port.



- A. Unplug the power supply plug from the charger and store the charger properly.
- B/C. Organize the charging plug's cable, then place it back inside the side door of the charging dock/workstation, and finally close the side door.

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

# Manual Docking



**Precautions:**None



A. Charging Dock



B. Workstation

Manually move the machine next to the charging dock/workstation. For instructions on how to Manually move the machine, refer to: Manual

Move;



Rotate the machine to align its charging electrodes with the electrodes on the charging dock.



Push the machine so that its charging electrodes make contact with the charging dock/workstation electrodes. Release the machine once the light strip on the charging dock/workstation turns green.



Check the machine's screen to confirm that the robot is charging.

Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

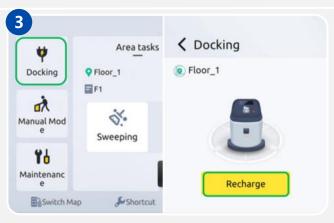
# **Auto Charging**



**Precautions:**None



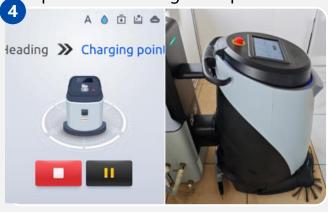
Log in to the machine using the password.



- 1. Tap "Docking."
- 2.Tap "Recharge," and the machine will automatically navigate back to the charging dock/workstation.



Check the Screen: Look at the machine's location icon to confirm that the positioning is normal. If the positioning is abnormal, refer to: <a href="Positioning Transfer">Positioning Transfer</a>; help the machine regain its position.



- 1.The machine will automatically navigate back to the charging dock/workstation and charge itself.
- 2. Charging in progress.

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

# Add Clean Water

# Method 1: Manual Water Filling

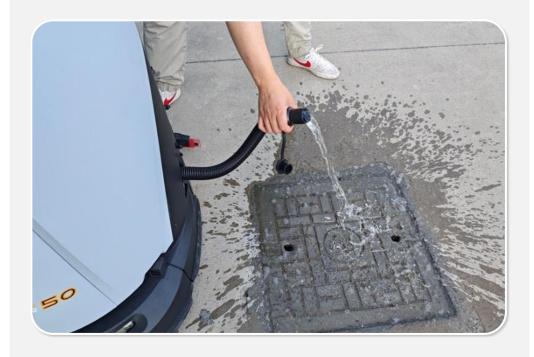


## Method 2: Automatic Water Filling



## Drain Clean Water

# Manual Water Drainage



Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

## Manual Water Filling



#### **Precautions:**

- 1. When adding water, do so slowly to prevent splashing water outside the tank.
- Pay attention to the water level in the clean water tank. Stop adding water when it reaches the maximum level line.

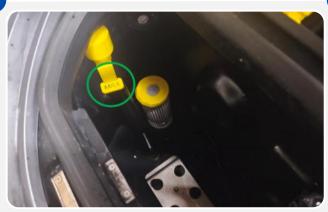




- 1. Open the top lid upwards.
- 2.Remove the secondary water tank by lifting it upwards.



Use a measuring bucket to pour clean water into the clean water tank.
Alternatively, you can use a water gun or hose to fill the clean water tank.



While filling the tank, monitor the water level inside. Stop adding water when the level reaches the maximum mark (MAX).



- 1.Reinsert the secondary water tank.
- 2.Close the top lid.

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

Manual Mode

Auto Mode

Scheduling

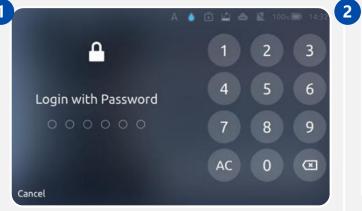
Positioning Transfer View Alarms

## **Automatic Water Filling**

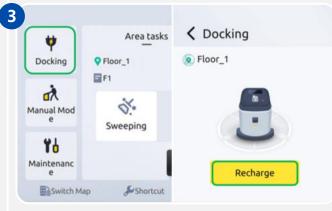


#### **Precautions:**

Automatic water filling can only be performed once the workstation setup is complete.



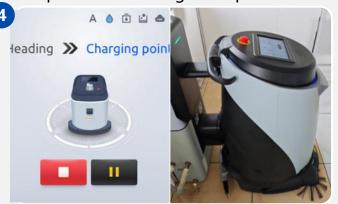
Log in to the machine using the password.



- 1. Tap "Docking."
- 2.Tap "Recharge," and the machine will automatically navigate back to the charging dock/workstation.



Check the Screen: Look at the machine's location icon to confirm that the positioning is normal. If the positioning is abnormal, refer to: <a href="Positioning Transfer">Positioning Transfer</a>; help the machine regain its position.



- 1. The machine will automatically navigate back to the workstation and refill itself with clean water.
- 2. Refueling in progress (charging, adding clean water, draining wastewater).;

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

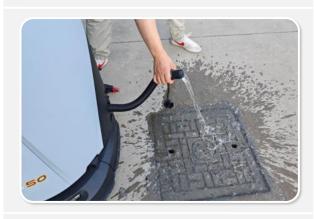
Manual Mode

Auto Mode

Scheduling

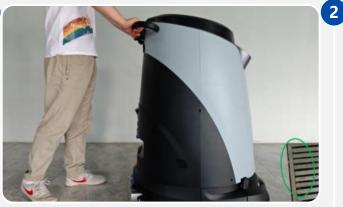
Positioning Transfer View Alarms

## Manual Water Drainage



**Precautions:**None

1



Manually move the machine to a location where manual water drainage is possible.



1.Remove the drain hose, keeping the hose end upright and higher than the wastewater tank's liquid level, then open the hose cap.

2. Tilt the drain hose outward to begin



Place the drain hose over the floor drain and wait for the wastewater to be fully drained.





- 1. Open the top lid upwards.
- 2.Remove the secondary water tank by lifting it upwards.

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

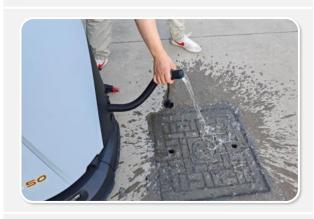
Emergency Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

# Manual Water Drainage



**Precautions:**None

5



Pull up and turn the yellow bolt inside the clean water tank counterclockwise to open the water drain plug at the bottom of the tank. Wait for the clean water to fully drain.



1.Reinsert the secondary water tank.2.Close the top lid.



After the clean water has fully drained, rotate the yellow bolt inside the clean water tank clockwise to close the water drain plug at the bottom of the tank.



1.Close the drain hose cap. 2.Store the drain hose.

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency Stop

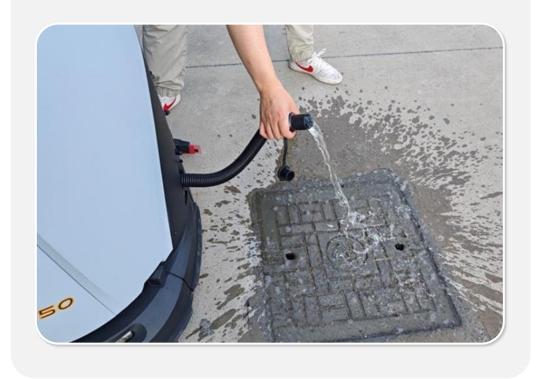
Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

#### Manual Wastewater Drainage



### Automatic Wastewater Drainage



Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

2

Scrubber 50 User Manual

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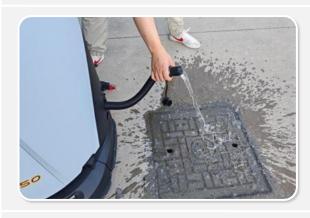
Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

#### Manual Wastewater Drainage



**Precautions:**None

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3



Manually move the machine to a location where manual water drainage is possible.



1.Remove the drain hose, keeping the hose end upright and higher than the wastewater tank's liquid level, then open the hose cap.

2. Tilt the drain hose outward to begin



Place the drain hose over the floor drain and wait for the wastewater to be fully drained.



1.Once the wastewater has fully drained, close the drain hose cap. 2.Store the drain hose.

Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

# Automatic Wastewater Drainage

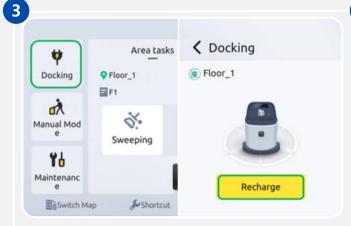


#### **Precautions:**

Automatic wastewater drainage can only be performed once the workstation setup is complete.



Log in to the machine using the password.

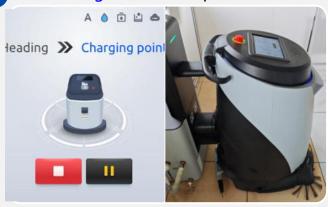


- 1. Tap "Docking."
- 2.Tap "Recharge," and the machine will automatically navigate back to the charging dock/workstation.



Check the Screen: Look at the machine's location icon to confirm that the positioning is normal. If the positioning is abnormal, refer to:

Positioning Transfer; help the machine



- 1. The machine will automatically navigate back to the workstation and refill itself with clean water.
- 2. Refueling in progress (charging, adding clean water, draining wastewater).;

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency Stop

Manual Mode

Auto Mode

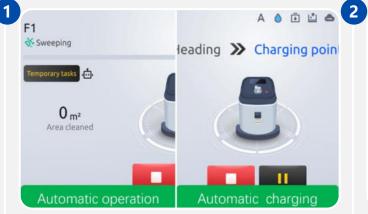
Scheduling

Positioning Transfer View Alarms

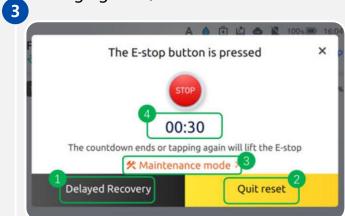
# **Emergency Stop**



**Precautions:**None



The machine is in the process of performing automatic cleaning tasks or automatically returning to the charging dock/workstation.



In emergency stop mode, the machine's drive motors are set to a locked state by default, preventing manual movement. To Manually move the machine, switch to maintenance mode and then enter Manual Moveing mode.



During automatic cleaning tasks or while the machine is automatically returning to the charging dock/workstation, if an emergency occurs, press the emergency stop button to bring the machine to an emergency stop.



Rotate the button clockwise to exit the emergency stop mode.

Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Man

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

## Manual Mode

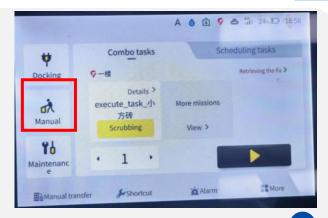


#### **Precautions:**

Before switching to different cleaning modes, verify that all cleaning accessories are properly installed.

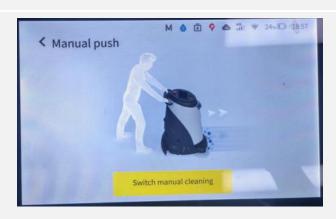


Install the cleaning accessories correctly according to the cleaning mode and the accessory configuration chart.



Tap "Manual Mode."





Tap "Switch to Manual Cleaning."



Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Man

Manual Mode

Auto Mode

Scheduling

6

Positioning Transfer View Alarms

## Manual Mode



#### **Precautions:**

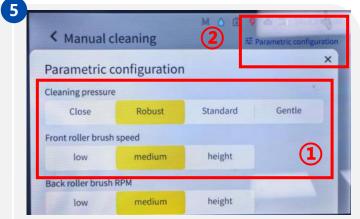
Before switching to different cleaning modes, verify that all cleaning accessories are properly installed.



- 1. Select the cleaning mode.
- 2. Tap "Device Level."

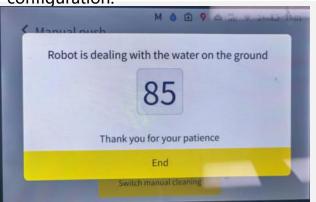


Manually move the machine to the area requiring cleaning.
If the machine cannot be moved, check the emergency stop button to ensure it is not activated.



1.Adjust the cleaning settings, such as suction power and spray level, according to your needs.

2.Tap "x" to close the Device Level configuration.



- 1.After cleaning is complete, tap "<" to exit manual cleaning mode.
- 2.If the scrubbing mode was used, the machine will handle any residual water on the floor. In this case, continue to move the machine forward for a short distance.

Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Manual Mode Auto Mode

Scheduling

Positioning Transfer View Alarms

# Auto Mode - Task List

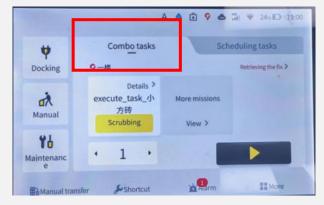


#### **Precautions:**

Before switching to different cleaning modes, verify that all cleaning accessories are properly installed.



Install the cleaning accessories correctly according to the cleaning mode and the accessory configuration chart.



Tap "Task List."

If "Task List" is not displayed on the screen, refer to: Auto Mode - Area

Tasks for instructions.



Check the Screen: Look at the machine's location icon to confirm that the positioning is normal. If the positioning is abnormal, refer to: <a href="Positioning Transfer">Positioning Transfer</a>; help the machine regain its position.

5

Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

6

Scrubber 50 User Manual

Manual Mode Auto Mode

Scheduling

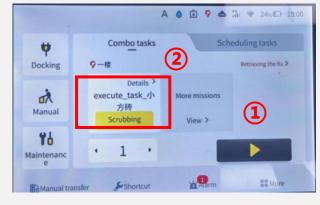
Positioning Transfer View Alarms

# Auto Mode - Task List

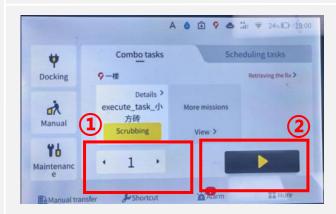


#### **Precautions:**

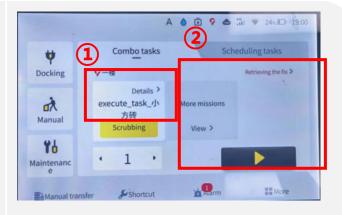
Before switching to different cleaning modes, verify that all cleaning accessories are properly installed.



- 1. Swipe left or right on the task list to find the required combined task by its name.
- 2. Tap the desired tasks.



- 1. Set the number of cycles for the tasks as needed.
- 2. Tap the start button to initiate the task.



- 1.Tap the yellow button to adjust the cleaning mode.
- 2&3. Select the desired cleaning mode, then tap "Confirm."



The machine starts automatic operation.

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

Manual Mode Auto Mode

Scheduling

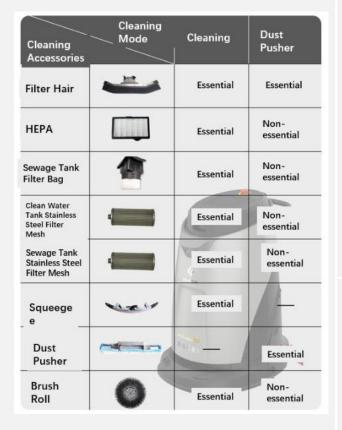
Positioning Transfer View Alarms

#### Auto Mode - Area Tasks

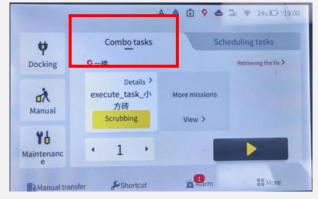


#### **Precautions:**

Before switching to different cleaning modes, verify that all cleaning accessories are properly installed.

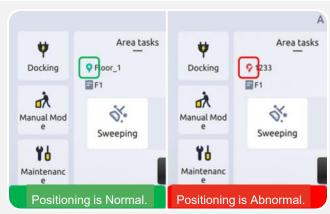


Install the cleaning accessories correctly according to the cleaning mode and the accessory configuration chart.



Tap "Area Tasks."

If "Area Tasks" is not displayed on the screen, refer to: Auto Mode - Task List for instructions.



Check the Screen: Look at the machine's location icon to confirm that the positioning is normal. If the positioning is abnormal, refer to: <a href="Positioning Transfer">Positioning Transfer</a>; help the machine regain its position.

2



Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal

Wastewater Drainage

**Scrubber 50 User** Manual

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Work sequence

Confirm

All floors



Manual Mode

**Auto** Mode

Scheduling

Positioning Transfer

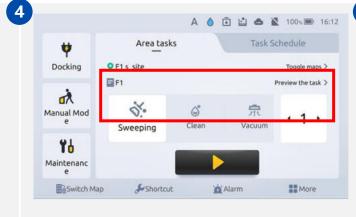
View Alarms

#### Auto Mode - Area Tasks

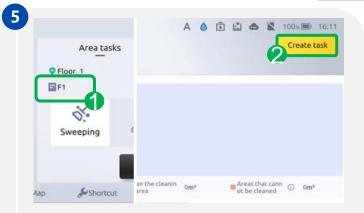


#### **Precautions:**

Before switching to different cleaning modes, verify that all cleaning accessories are properly installed.



Tap the task bar.

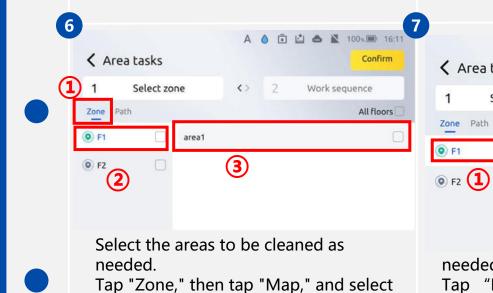


Tap "Create Task."

Select zone

area1

2



the names of the areas to be cleaned.

needed.

Area tasks

Zone Path

Tap "Path," then tap "Map," select the names of the paths to be cleaned, and tap "Next."

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Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Star

Manual Mode Auto Mode

Scheduling

Positioning Transfer View Alarms

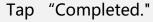
#### Auto Mode - Area Tasks

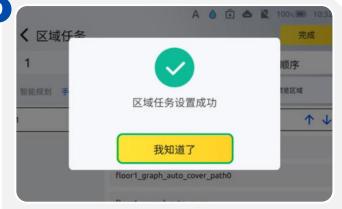


#### **Precautions:**

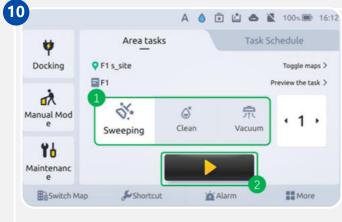
Before switching to different cleaning modes, verify that all cleaning accessories are properly installed.







Tap "Got it."



- 1.Tap "Cleaning Mode."
- 2.Set the number of cycles for this task.
- 3. Tap the start button to initiate the task.



The machine starts automatic operation.

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

Manual Mode Auto Mode

Scheduling

Positioning Transfer View Alarms

# Pause/End Auto Mode



#### **Precautions:**

None



If the machine is in automatic operation, press the emergency stop button.

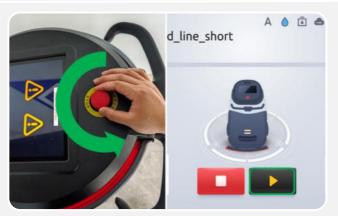


At this point, the automatic operation has been paused.

To end the automatic operation early, tap the "End" button on the screen.



If the screen is locked, first log in with your password. After logging in, tap "x" to dismiss the emergency stop reminder.



To resume the automatic operation after pausing, first rotate the emergency stop button clockwise to reset it, then tap the "Resume" button on the screen.

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal

View

Alarms

Wastewater Drainage

Scrubber 50 User Manual

Emergency

Manual Mode

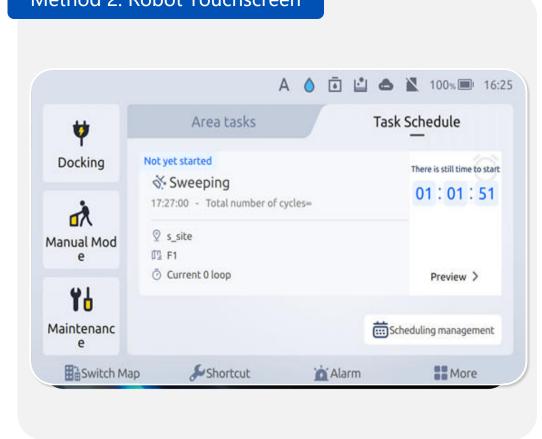
Auto Mode

Scheduling

Positioning Transfer

Method 2: Robot Touchscreen





Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Manual Mode

Auto Mode

Scheduling

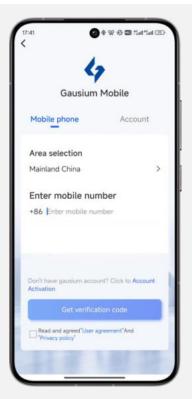
Positioning Transfer View Alarms

### Create Schedules - Mobile App



#### **Precautions:**

To set Do Not Disturb mode, select "Breaks" as the scheduling option when creating the schedule.



Open the "Gausium Mobile" app and log in with your account.

If you do not have an account, please contact Gausium's after-sales engineer.



1.Tap "Robot."
2.In the list of your robots, find and select the corresponding robot.

If the robot is not listed, please contact Gausium's aftersales engineer.



Tap the icon ⊕ in the top right corner.

Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Start

Manual Mode

Auto Mode

Scheduling

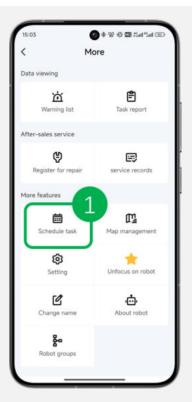
Positioning Transfer View Alarms

## Create Schedules - Mobile App



#### **Precautions:**

To set Do Not Disturb mode, select "Breaks" as the scheduling option when creating the schedule.



Tap "Task Schedule" .



Tap the icon in the top right corner.



1.Tap "Task Type."
2.Choose "Quantity," "Time,"

or "Break."

**Quantity**: Set the start time and the number of cycles.

Time: Set the start and end times.

**Break**: Set a time period during which the machine will enter Do Not Disturb mode.





Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Startt

Manual Mode

Auto Mode

Scheduling

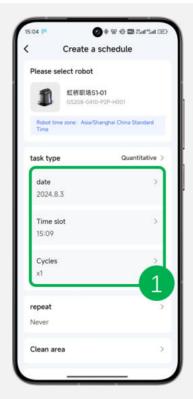
Positioning Transfer View Alarms

Create Schedules - Mobile App

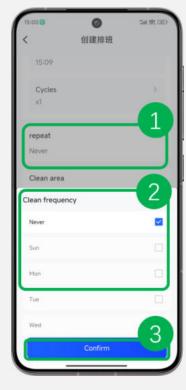


#### **Precautions:**

To set Do Not Disturb mode, select "Breaks" as the scheduling option when creating the schedule.



Set the date to start the scheduled task and specify the time period for the task execution.

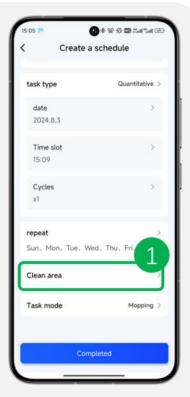


1.Tap "Repeat."

2.Select the days of the week.3.Tap "Confirm" to set the

scheduling task' s repeat cycle by the week.

**Never**: The scheduled task will not repeat and will only be executed once on the specified start date.



Tap "Cleaning Location."



Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Startt

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

#### Create Schedules - Mobile App

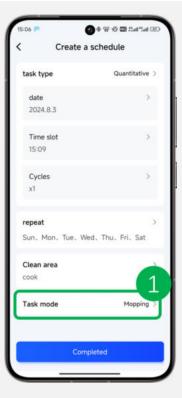


#### **Precautions:**

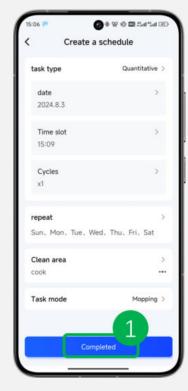
To set Do Not Disturb mode, select "Breaks" as the scheduling option when creating the schedule.



1.Tap "Choose a Location" and choose the map for the scheduled task.
2.Tap "Where to Clean" and select the areas to be cleaned for the scheduled task; multiple selections are allowed.
3.Tap "Confirm."



Tap "Mode" to configure the cleaning mode for the scheduled task.



Tap "Completed" to complete the setup of the scheduled task.



Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Sta

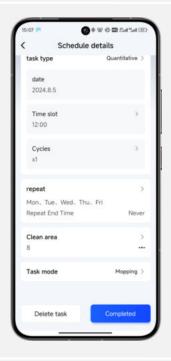
Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

### Delete/Edit Schedules - Mobile App



#### **Precautions:**

To set Do Not Disturb mode, select "Breaks" as the scheduling option when creating the schedule.



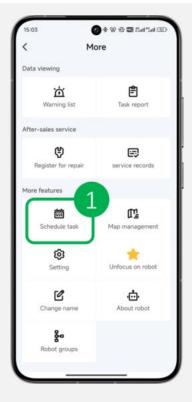
1.Tap "Robot."

2.In the list of your robots, find and select the corresponding robot.

If the robot is not listed, please contact Gausium's aftersales engineer.



Tap the icon in the top right corner.



Tap "Task Schedule" .



Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Startt

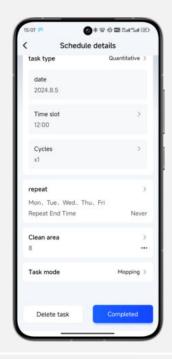
Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

### Delete/Edit Schedules - Mobile App

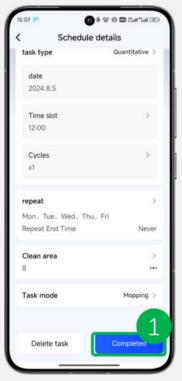


#### **Precautions:**

To set Do Not Disturb mode, select "Breaks" as the scheduling option when creating the schedule.

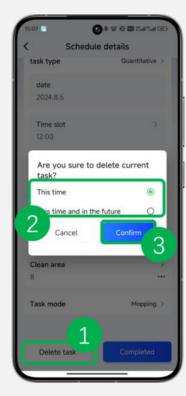


In the schedule task calendar, find and tap the task you want to edit.



#### **Edit:**

Adjust the scheduled task settings as needed, then tap "Completed" after making the changes.



#### **Delete:**

1.Tap "Delete Task." 2.Choose to delete "This Task Only" or "This and All Future Tasks."

3.Tap "Confirm."







Appearance Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

## Startu

Manual Mode

Auto Mode

Scheduling

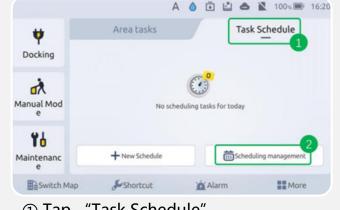
Positioning Transfer View Alarms

### Create Schedules - Touchscreen

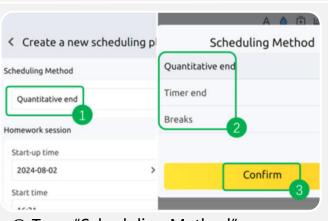


#### **Precautions:**

To set Do Not Disturb mode, select "Breaks" as the scheduling option when creating the schedule.

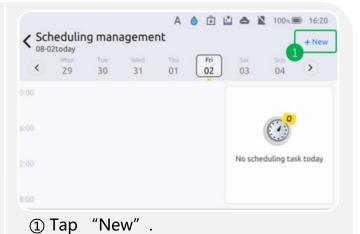


- ① Tap "Task Schedule".
- ② Tap "Scheduling Management".

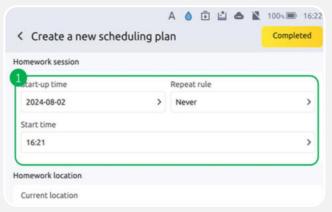


- ① Tap "Scheduling Method".
- ② Select a scheduling method.
- ③ Tap "Confirm."





2



① Set the operation time period.



Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Startu

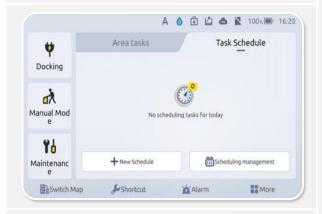
Manual Mode

Auto Mode

Scheduling

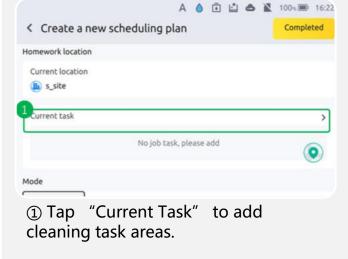
Positioning Transfer View Alarms

### Create Schedules - Touchscreen

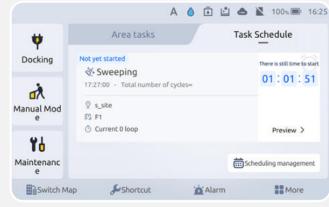


#### **Precautions:**

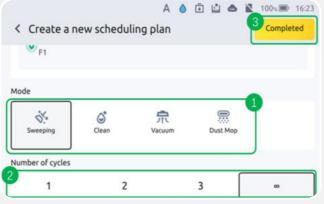
To set Do Not Disturb mode, select "Breaks" as the scheduling option when creating the schedule.







The task scheduling is complete.



- ① Set the operation mode.
- ② Set the number of cycles.
- ③ Tap "Completed."





Stop

Startup

Shutdown

Manual Move

3

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual



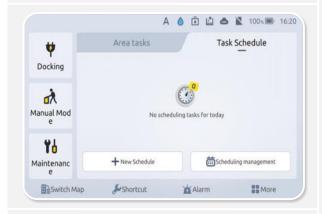
Manual Mode

Auto Mode

Scheduling

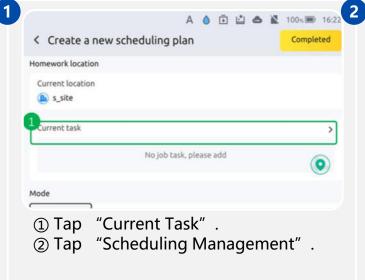
Positioning Transfer View Alarms

### Delete/Edit Schedules - Touchscreen



#### **Precautions:**

To set Do Not Disturb mode, select "Breaks" as the scheduling option when creating the schedule.

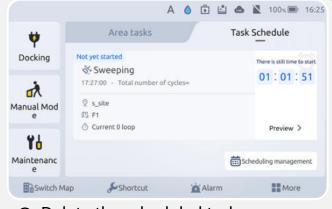


Create a new scheduling plan

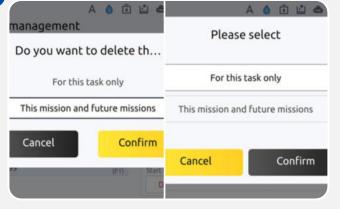
Create a new scheduling plan

Clean

① Tap the scheduled task you want to edit or delete.



- A Delete the scheduled task.
- B Edit the scheduled task.



When editing or deleting a scheduled task, you need to select the range of changes: either "This Task Only" or "This and All Future Tasks."



Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

# **Positioning Transfer**

After manual transfer or a loss of positioning, the machine requires manual assistance to complete positioning initialization;

Scrubber 50 supports three methods for positioning initialization.

Method 1: Manual Docking



Method 2: Move to a Specified Location



Method 3: Scan QR Code



Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal

Wastewater Drainage

**Scrubber 50 User** Manual

Manual Mode

Auto Mode

Scheduling

**Positioning** Transfer

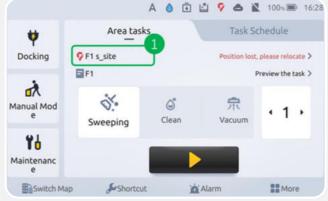
View Alarms

# Manual Docking



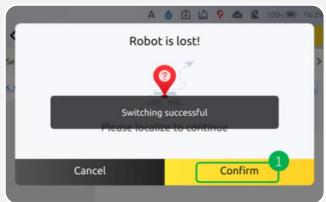
#### **Precautions:**

To use this positioning method, a charging dock/workstation must be deployed on the corresponding map of the current location.



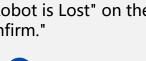
If positioning issues occur or after the machine completes a manual transfer, tap "Position Lost, Please Relocate."

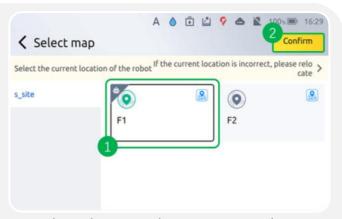




When seeing "Robot is Lost" on the screen, tap "Confirm."

3

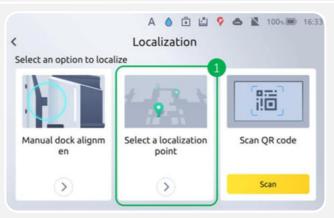




1. Select the map that corresponds to the machine's current actual location.

2





"Manual Docking."



Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

# **Manual Docking**



#### **Precautions:**

To use this positioning method, a charging dock/workstation must be deployed on the corresponding map of the current location.

5



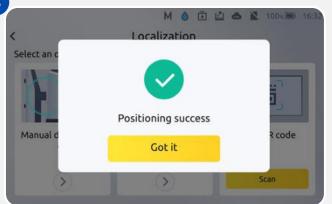
Manually move the machine to the charging dock/workstation.



Rotate the machine to align its charging electrodes with those of the charging dock/workstation.



Move the machine so that its charging electrodes make contact with the charging dock/workstation electrodes. Release once the light strip on the charging dock/workstation turns green.



When a successful positioning message appears on the screen and you hear the machine's voice prompt saying, "Positioning Success," it indicates that the machine has successfully completed positioning initialization.

Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Manu

Manual Mode

Auto Mode

Scheduling

Positioning Transfer View Alarms

### Move to a Specified Location

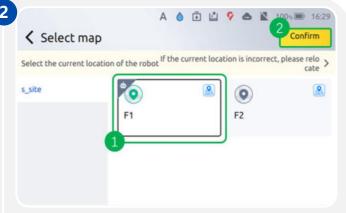


#### **Precautions:**

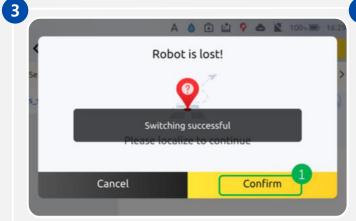
To use this positioning method, ensure that the corresponding map of the current location includes designated points for positioning.



If positioning issues occur or after the machine completes a manual transfer, tap "Position Lost, Please Relocate."



1.Select the map that corresponds to the machine's current actual location. 2.Tap "Confirm."



When seeing "Robot is Lost" on the screen, tap "Confirm."



Tap "Select a Localization Point".

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

Manual Mode

Auto Mode

Scheduling

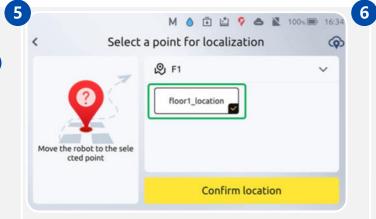
Positioning Transfer View Alarms

### Move to a Specified Location

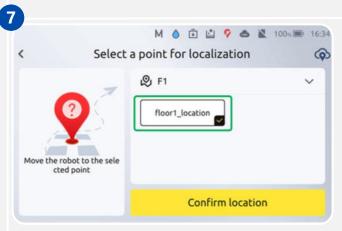


#### **Precautions:**

To use this positioning method, ensure that the corresponding map of the current location includes designated points for positioning.



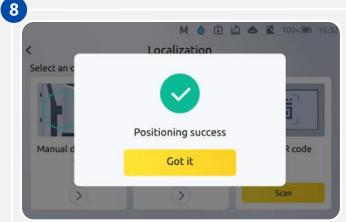
Select the designated point for positioning.



Once the machine reaches the designated location, tap "Confirm Location" on the screen.



Move the machine near the actual location corresponding to the designated point.



When a successful positioning message appears on the screen and you hear the machine's voice prompt saying, "Positioning Success," it indicates that the machine has successfully completed positioning initialization.

Emergency

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Starte

Manual Mode

Auto Mode

Scheduling

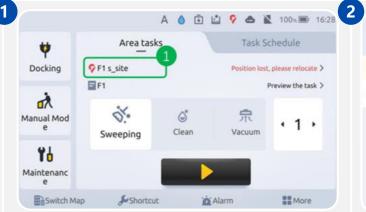
Positioning Transfer View Alarms

# Scan QR Code

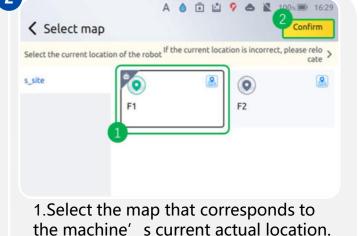


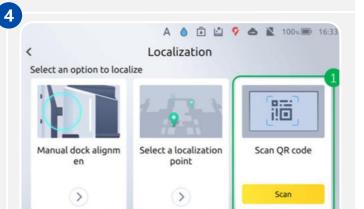
#### **Precautions:**

To use this positioning method, the corresponding map of the current location must have QR code points deployed.



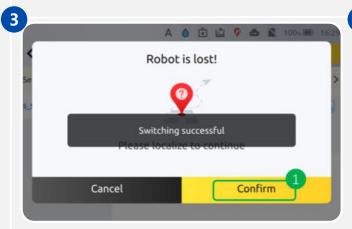
If positioning issues occur or after the machine completes a manual transfer, tap "Position Lost, Please Relocate."





Select "Scan QR Code."

2.Tap "Confirm."



When seeing "Robot is Lost" on the screen, tap "Confirm."

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

Manual Mode

Auto Mode

Scheduling

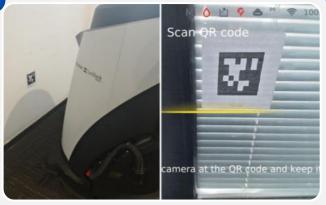
Positioning Transfer View Alarms

# Scan QR Code

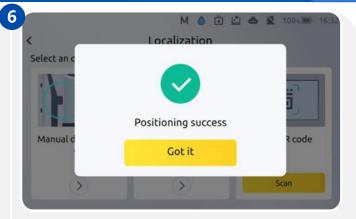


#### **Precautions:**

To use this positioning method, the corresponding map of the current location must have QR code points deployed.



Move the machine directly in front of the QR code, positioning it 20-30 cm away, and ensure the QR code is centered on the machine's screen.



After the machine scans the QR code, a successful positioning message will appear on the screen, and you will hear the machine's voice prompt saying, "Positioning Success," indicating that the machine has successfully completed positioning initialization.

Stop

Startup

Shutdown

Manual Move

Charging

Clean Water Disposal Wastewater Drainage

Scrubber 50 User Manual

Emergency

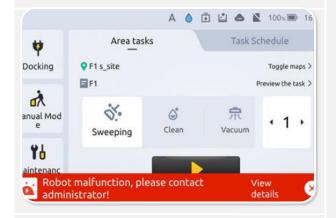
Manual Mode

Auto Mode

Scheduling

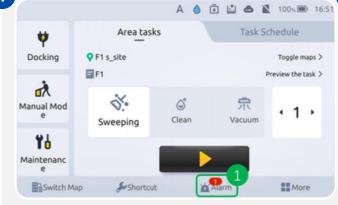
Positioning Transfer View Alarms

# **View Alarms**

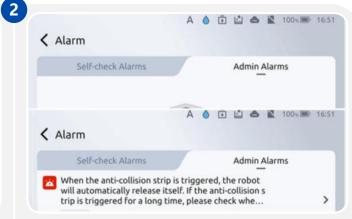


#### **Precautions:**

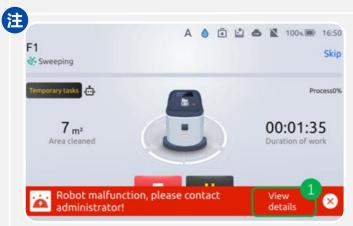
If the alarm cannot be resolved using the provided solutions, please promptly contact a Gausium engineer.



If the screen is locked, log in with your password first, then tap "Alarm" in the bottom corner.



- 1.The machine is operating normally with no alarms.
- 2. The machine has encountered an issue and shows an alarm message.



When the machine encounters an alarm, a red popup will appear at the bottom of the screen. Tap "View Details" to quickly access the alarm information.



# Robolution by Gausium